



DIPLOMA WING

# RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL

SCHEME OF STUDIES & EXAMINATIONS ( IMPLEMENTED FROM SESSION : JULY 2023)

SCHEME
OCBC JULY2022/ 2023

NAME OF BRANCH
PRODUCTION ENGINEERING

BRANCH CODE
P05

SEMESTER
FIFTH (V)

S.N.	PAPER CODE	SUBJECT CODE	SUBJECT NAME	THEORY COMPONENT						PRACTICAL COMPONENT					TOTAL CREDITS	TOTAL MARKS		
				HRS PER WEEK	CREDITS	TERM WORK			THEORY PAPER		HRS PER WEEK	CREDITS	LAB WORK	PRACTICAL EXAM/VIVA				
						QUIZ/ASSIGNMENT	MID TERM TEST*		TOTAL	MARKS				DURATION			MARKS	DURATION
							I	II										
1	7413	501	THEORY OF MACHINES & MECHANISMS	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
2	7414	502	INDUSTRIAL ENGINEERING AND MANAGEMENT	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
3	7546	503	MECHATRONICS AND ROBOTICS	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
4	7547	504	AUTOMATION AND CNC MACHINES	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
5	7416	511	POWER PLANT ENGINEERING OR	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
	7417	512	FARM EQUIPMENT AND FARM MACHINERY															
6	7548	521	ADVANCED MANUFACTURING PROCESSES OR	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
	7549	522	OPERATIONS RESEARCH															
7	7601	531	RENEWABLE ENERGY TECHNOLOGIES OR	3	3	10	10	10	30	70	03 Hrs.	0	0	0	0	0	3	100
	7602	532	INTERNET OF THINGS															
8			CAD/CAM LAB	0	0	0	0	0	0	0	0	2	1	20	30	03 Hrs.	1	50
9			SUMMER INTERNSHIP-II**	0	0	0	0	0	0	0	0	0	3	20	30	03 Hrs.	3	50
10			MAJOR PROJECT***	0	0	0	0	0	0	0	0	2	0	0	0	0	0	0
11			WORKSHOP/SEMINAR/VISIT etc.	0	0	0	0	0	0	0	0	5	0	0	0	0	0	0
12			RECOVERY CLASSES/LIBERARY etc.	0	0	0	0	0	0	0	0	6	0	0	0	0	0	0
TOTAL				21	21				210	490		15	4	40	60		25	800

- NOTE -**
- (1)\* Two Best, out of Three Mid Term Tests (Progressive Tests) Marks should be entered here.
  - (2)\*\* 4-6 Weeks Summer Internship after IV Semester.
  - (3)\*\*\*One Credit will be carried forward to the Six semester major project evaluation.

GRAND TOTAL OF CREDITS
25

GRAND TOTAL OF MARKS
800



**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	THEORY OF MACHINES AND MECHANISMS
PAPER CODE	:	7413
SUBJECT CODE	:	501
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objectives:**

- To understand different types of cams and their motions and also to draw cam profiles for various motions.
- To understand the mechanism of various types of drives available for transmission of power.
- To understand the design of Brakes, Dynamometers, Bearings and Clutches and their function and working.
- To understand the need for balancing of masses in the same plane
- To Know different types of governors.

**Course Content:**

**UNIT I: Cams and Followers:** Concept; Definition and application of Cams and Followers; Classification of Cams and Followers; Different follower motions and their displacement diagrams like uniform velocity, SHM, uniform acceleration and Retardation; Drawing of profile of radial cam with knife-edge and roller follower with and without offset with reciprocating motion (graphical method).

**UNIT II: Power Transmission:** Types of Drives – Belt, Chain, Rope, Gear drives & their comparison; Belt Drives - flat belt, V- belt & its applications; Material for flat and V-belt; Angle of lap, Belt length. Slip and Creep; Determination of Velocity Ratio, Ratio of tight side and slack side tension; Centrifugal tension and Initial tension; Condition for maximum power transmission (Simple numericals); Chain Drives – Advantages & Disadvantages; Selection of Chain & Sprocket wheels; Methods of lubrication; Gear Drives – Spur gear terminology; Types of gears and gear trains, their selection for different applications; Train value & Velocity ratio for compound, reverted and simple epicyclic gear train; Methods of lubrication; Law of gearing; Rope Drives – Types, applications, advantages & limitations of Steel ropes.

**UNIT III: Flywheel and Governors:** Flywheel - Concept, function and application of flywheel with the help of turning moment diagram for single cylinder 4-Stroke I.C. Engine (no Numericals); Co-efficient of fluctuation of energy, Coefficient of fluctuation of speed and its significance; Governors - Types and explanation with neat sketches (Centrifugal, Watt and Porter); Concept, function and applications & Terminology of Governors; Comparison between Flywheel and Governor.

**UNIT IV: Brakes, Dynamometers, Clutches & Bearings:** Function of brakes and dynamometers; Types of brakes and Dynamometers; Comparison between brakes and dynamometers; Construction and working of i) shoe brake, ii) Band Brake, iii) Internal expanding shoe brake iv) Disc Brake; Concept of Self Locking & Self energizing brakes; Numerical problems to find braking force and braking torque for shoe & band brakes; Construction and working of i) Rope Brake Dynamometer, ii) Hydraulic Dynamometer, iii) Eddy current Dynamometers; Clutches- Uniform pressure and Uniform Wear theories; Function of Clutch and its application; Construction and working of i) Single plate clutch, ii) Multiplate clutch, iii) Centrifugal Clutch iv) Cone clutch and v) Diaphragm clutch. (Simple numericals on single and Multiplate clutch); Bearings – i) Simple Pivot, ii) Collar Bearing, iii) Conical pivot. Torque & power lost in friction (no derivation). Simple numericals.

**UNIT V: Balancing & Vibrations:** Concept of balancing; Balancing of single rotating mass; Graphical method for balancing of several masses revolving in same plane; Concept and terminology used in vibrations, Causes of vibrations in machines; their harmful effects and remedies.

**Reference Books:**

1. Theory of machines – S.S .Rattan ,Tata McGraw-Hill publications.
2. Theory of machines – R.K.Bansal ,Laxmi publications
3. Theory of machines – R.S. Khurmi & J.K.Gupta , S.Chand publications.
4. Dynamics of Machines – J B K Das, Sapna Publications.
5. Theory of machines – Jagdishlal, Bombay Metro – Politan book Ltd.

**Course outcomes:**

At the end of the course, the student will be able to:

C01	Know different machine elements and mechanisms.
C02	Understand Kinematics and Dynamics of different machines and mechanisms.
C03	Select Suitable Drives and Mechanisms for a particular application.
C04	Appreciate concept of balancing and Vibration.
C05	Develop ability to come up with innovative ideas.
C06	Understand different types of cams and their motions and also draw cam profiles for various motions

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**DIPLOMA IN PRODUCTION ENGINEERING (P05)**  
**SEMESTER V**

COURSE TITLE	:	INDUSTRIAL ENGINEERING AND MANAGEMENT
PAPER CODE	:	7414
SUBJECT CODE	:	502
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objectives:**

- To take the right decisions to optimize resources utilization by improving productivity of the Lands, Buildings, People, Materials, Machines, Money, Methods and Management effectively.
- To eliminate unproductive activities under the control of the Management, Supervisor, worker and the Design of Products and Processes.
- To use the Charts to record the Activities of the people, materials and Equipment to find alternative methods which minimize waste and to implement the best method.

**Course Content:**

**UNIT-I: Plant Engineering:** Plant; Selection of site of industry; Plant layout; Principles of a good layout; Types; Process; Product and Fixed position; Techniques to improve Layout; Principles of Material handling equipment; Plant maintenance; Importance; Break down maintenance; Preventive maintenance and Scheduled maintenance.

**Plant Safety:** Importance; Accident: Causes and Cost of an Accident, Accident Proneness, Prevention of Accidents; Industrial disputes; Settlement of Industrial disputes; Collective bargaining; Conciliation; Mediation; Arbitration; Indian Factories Act 1948 and its provisions related to health, welfare and safety.

**UNIT-II: Work Study:** Productivity; Standard of living; Method of improving Productivity; Objectives; Importance of good working conditions.

**Method Study:** Definition; Objectives; Selection of a job for method study; Basic procedure for conduct of Method study; Tools used; Operation process chart; Flow process chart; Two handed process chart; Man Machine chart; String diagram and flow diagram.

**Work Measurement:** Definition; Basic procedure in making a time study; Employees rating factor; Application of time allowances: Rest, Personal, Process, Special and Policy allowances; Calculation of standard time; Numerical Problems; Basic concept of production study; Techniques of Work Measurement; Ratio delay study; Synthesis from standard data; Analytical estimating and Pre determined Motion Time System (PMTS).

**UNIT-III: Production Planning and Control:** Introduction; Major functions of Production Planning and Control; Pre planning; Methods of forecasting; Routing and Scheduling; Dispatching and Controlling; Concept of Critical Path Method (CPM); Types of Production: Mass Production, Batch Pro-

duction and Job Order Production; Characteristics; Economic Batch Quantity (EBQ); Principles of Product and Process Planning; Make or Buy decision; Numerical problems.

**Quality Control:** Definition; Objectives; Types of Inspection: First piece, Floor and Centralized Inspection; Advantages and Disadvantages; Statistical Quality Control; Types of Measurements; Method of Variables; Method of Attributes; Uses of X, R, p and c charts; Operating Characteristics curve (O.C curve); Sampling Inspection; Single and Double Sampling plan; Concept of ISO 9001:2008 Quality Management System Registration/Certification procedure; Benefits of ISO to the organization.

**UNIT-IV: Principles of Management:** Definition of Management; Administration; Organization; F.W. Taylor's and Henry Fayol's Principles of Management; Functions of Manager; Types of Organization: Line, Staff, Taylor's Pure functional types; Line and staff and committee type; Directing; Leadership; Styles of Leadership; Qualities of a good leader; Motivation; Positive and Negative Motivation; Modern Management Techniques; Just In Time; Total Quality Management (TQM); Quality circle; Zero defect concept; 5S Concept; Management Information Systems. **Personnel Management:** Responsibility of Human Resource Management; Selection Procedure; Training of Workers; Apprentice Training; On the Job training and Vestibule School Training; Job Evaluation and Merit Rating; Objectives and Importance; Wages and Salary Administration; Components of Wages; Wage Fixation; Type of Wage Payment: Halsey's 50% Plan, Rowan's Plan and Emerson's efficiency plan; Numerical Problems.

**UNIT-V: Financial Management:** Fixed and Working Capital; Resources of Capital; Shares Preference and Equity Shares; Debentures; Type of debentures; Public Deposits; Factory Costing: Direct Cost; Indirect Cost; Factory Overhead; Selling Price of a product; Profit; Numerical Problems; Depreciation; Causes; Methods: Straight line, sinking fund and percentage on Diminishing Value Method; Numerical Problems.

**Material Management:** Objectives of good stock control system; ABC analysis of Inventory; Procurement and Consumption cycle; Minimum Stock, Lead Time, Reorder Level-Economic Order Quantity problems; Supply Chain.

#### Reference Books:

1. Industrial Engineering & Management, S.C. Sharma, Khanna Book Publishing Co. (P) Ltd., Delhi
2. Industrial Engineering and Management, O.P. Khanna, Revised Edition, Dhanpat Rai Publications (P) Ltd., New Delhi – 110002.
3. Management, A global perspective, Heinz Wehrich, Harold Koontz, 10<sup>th</sup> Edition, McGraw Hill International Edition 1994.
4. Essentials of Management, 4th Edition, Joseph L.Massie, Prentice-Hall of India, New Delhi 2004.
5. Principles and Practices of Management, Premvir Kapoor, Khanna Publishing House, N. Delhi

#### Course outcomes:

At the end of the course, the student will be able to:

CO1	Explain the different types of layout and plant maintenance with safety
CO2	List and explain the need of method study and work measurements
CO3	Explain the production planning and quality control, and its functions
CO4	Understand the basic principles, approaches and functions of management and identify concepts to specific situations
CO5	List and explain the different financial sources and methods of inventory management

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**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	MECHATRONICS AND ROBOTICS
PAPER CODE	:	7546
SUBJECT CODE	:	503
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Learning Objectives**

- To understand the basic concepts and characteristics of measurement systems.
- To learn various types of sensors and transducers various mechanical, electrical and pneumatic actuation systems.
- To learn the concepts of digital communications and develop PLC programs.
- To introduce the basic concepts, parts of robots and types of robots.
- To make the student familiar with the various drive systems for robot, sensors and their applications in robots and programming of robots.

**Course Content:**

**UNIT-I: Introduction:** Mechatronic systems, closed and open loop measurement systems, The Mechatronics approach, Sensors microprocessors and transducers, displacement, position and proximity pickups. Mechanical and Electrical activation systems.

**Measurement Systems:** Measurement errors, modelling measurement systems, system, Reliability, signal conditioning & processing, Data acquisition and processing systems, Data presentation.

**Applied Instrumentation:** Measurement of mechanical and process parameters. Measurement of force, torque, temperature, pressure and flow. Measurement of displacement velocity and acceleration. Measurement of noise and vibration

**UNIT-II: Programmable Logic Controller (PLC):** Definition – Basic block diagram and structure of PLC – Input/Output processing – PLC Programming: Ladder diagram, its logic functions, latching and sequencing – PLC mnemonics – Timers, internal relays and counters – Shift registers – Master and jump controls – Data handling – Analog input/output – Selection of PLC.

**UNIT-III: Fundamentals of Robot:** Robot – Definition – Co-ordinate Systems, Work Envelope, types and classification – Specifications – Pitch, Yaw, Roll, Joint Notations, Speed of Motion, Pay Load – Basic robot motions - Point to point control, Continuous path control. Robot Parts and Their Functions – Need for Robots – Different Applications. Robot drive systems and end effectors: Pneumatic Drives – Hydraulic Drives – Mechanical Drives – Electrical Drives – D.C. Servo Motors, Stepper Motor, A.C. Servo Motors – Salient Features, Applications and Comparison of all these Drives. End Effectors – Grippers – Mechanical Grippers, Pneumatic and Hydraulic Grippers, Magnetic Grippers, Vacuum Grippers; Two Fingered and Three Fingered Grippers; Internal Grippers and External Grippers; Selection and Design Considerations

**UNIT-IV: Sensors and Machine Vision:** Requirements of a sensor, Principles and Applications of the following types of sensors – Position of sensors (Piezo Electric Sensor, LVDT, Resolvers, Optical Encoders), Range Sensors (Triangulation Principle, Structured, Lighting Approach, Laser Range Meters), Proximity Sensors (Inductive, Capacitive, and Ultrasonic), Touch Sensors, (Binary Sensors, Analog Sensors), Wrist Sensors, Compliance Sensors, Slip Sensors. Camera, Frame Grabber, Sensing and Digitizing Image Data – Signal Conversion, Image Storage, Lighting Techniques.

**UNIT-V: Robot kinematics and Robot Programming:** Forward Kinematics, Inverse Kinematics and Differences; Forward Kinematics and Reverse Kinematics of Manipulators with Two Degrees of Freedom (In 2 Dimensional) – Deviations and Problems. Teach Pendant Programming, Lead through programming, Robot programming Languages – VAL Programming – Motion Commands, Sensor Commands, End effector commands, and Simple Programs Industrial Applications: Application of robots in machining, welding, assembly, and material handling.

**Reference Books:**

1. Mechatronics W. Bolton, Pearson Education, Asia 2007
2. A Text Book on Mechatronics, R. K. Rajput, S. Chand & Co, New Delhi 2011
3. K.S. Fu., R.C.Gonzalez, C.S.G.Lee, “ Robotics Control sensing “, Vision and Intelligence, McGraw Hill International Edition, 1987.
4. M. P. Groover, “Industrial Robotics – Technology, Programming and Applications”, McGraw-Hill, 2001
5. Fu. K. S. Gonzalz. R. C., and Lee C.S.G., “Robotics Control, Sensing, Vision and Intelligence”, McGraw-Hill Book Co., 1987
6. Yoram Koren, “Robotics for Engineers”, McGraw-Hill Book Co., 1992
7. Janakiraman. P. A., “Robotics and Image Processing”, Tata McGraw-Hill, 1995
8. Elements of Robotics Process Automation, Mukherjee, Khanna Publishing House, Delhi, 2018

**Course outcomes:**

At the end of the course, the student will be able to:

CO1	Describe about various types of sensors and transducers.
CO2	Explain the various mechanical, electrical and pneumatic actuation systems.
CO3	Explain the basic PLC architecture and PLC programming concepts.
CO4	Explain the robot anatomy, classification, characteristics of robot, advantages and disadvantages.
CO5	Explain about various types of sensors and concepts on robot vision system.





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**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	AUTOMATION AND CNC MACHINES
PAPER CODE	:	7547
SUBJECT CODE	:	504
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Learning Objectives:**

- To understand basics of industrial automation
- To identify various types of automation
- To create CAM Tool path and NC- G code output.

**Course Content:**

**UNIT-I: Introduction:** Basic concept of Automation, Types of Automation, Feasibility etc, Industrial Hydraulics: Introduction, basic concepts, Hydraulic fluids, Classification and properties of hydraulic fluids, Contaminates in hydraulic system, control and cleanliness standards, Fluid power generators, i.e. Gear, Vane, Piston pumps, linear and Rotary Actuators, Direction Control Valves, types, actuation methods, pressure control valves; pressure reducing valves, pressure relief valve, Unloading valve, Sequence valve, Counterbalance valve, Flow control valves simple and pressure compensated type.

**UNIT-II: Pneumatics:** Introduction, Basic components, Source, storage and distribution, treatment of compressed air, linear and Rotary actuators, Direction control valves – types, actuation methods, pressure control valves, logic devices – twin pressure valve, shutter valve, time delay valve, Pneumatic circuit design and analysis, conventional as well as computer aided design. Robotics: Basic concepts, classification based on Geometry, programming, drives, work volume of robots world and joint coordinates various joints, DOF, end effectors – Types and uses, Sensors in Robots, programming – Teach pendant and Computer programming

**UNIT-III: Automatic Assembly System:** Development of Automatic Assembly process, Transfer de-

vices – continuous, Intermittent, synchronous and asynchronous, Vibratory feeders – Mechanics, effect of frequency, acceleration, track angle, friction, load sensitivity, orientation of parts – active and passive devices, Mechanical feeders – computation and operational details, feed tracks, Escapement devices. Product design for high-speed automatic assembly, examples of design modifications.

**UNIT-IV: CNC Machine and Components:** CNC Machines: Numerical control – definition – components of NC systems – development of NC – DNC – Adaptive control systems – working principle of a CNC system – Features of CNC machines - advantage of CNC machines – difference between NC and CNC – Construction and working principle of turning centre – Construction and working principle of machining centers – machine axes conventions turning centre and machining centre – design considerations of NC machine tools. CNC EDM machine – Working principle of die sinking and wire EDM machines - Coordinate Measuring Machines: construction and working principles.

Drives: spindle drive – dc motor – Feed drives – dc servo motor and stepper motor – hydraulic systems – Slide ways – requirement – types – friction slide ways and anti-friction slide ways - linear motion bearings – recirculation ball screw – ATC – tool magazine – feedback devices – linear and rotary transducers – Encoders - in process probing.



**UNIT-V: Part Programming:** NC part programming – methods – manual programming – conversational programming – APT programming - Format: sequential and word address formats - sequence number – coordinate system – types of motion control: point-to-point, paraxial and contouring – Datum points: machine zero, work zero, tool zero NC dimensioning – reference points – tool material – tool inserts - tool offsets and compensation - NC dimensioning – preparatory functions and G codes, miscellaneous functions and M codes – interpolation: linear interpolation and circular interpolation - CNC program procedure. Part Program – macro – sub-program – canned cycles: stock – mirror images – thread cutting – Sample programs for lathe: Linear and circular interpolation - Stock removal turning – Peck drilling – Thread cutting and Sample programs for milling: Linear and circular interpolation – mirroring – sub program – drilling

**Reference Books:**

1. Anthony Esposito, “Fluid Power with Application”, 5th Edition, Pearson Education (2003).
2. Majumdar S R, “Oil Hydraulic System”, Tata McGraw Hill (2001).
3. Bolton W, “Mechatronics”, 2nd Edition, Pearson Education, New Delhi (1999).
4. Necsulelscu Dan, “Mechatronics”, Pearson Education, New Delhi (2002).
5. Geoffrey Boothroyd, “Assembly Automation and Product Design”, Marcel Dekker Inc (1991).
6. CNC Programming, S. K. Sinha, Galgotia Publications Pvt. Ltd.
7. Computer Control of Manufacturing Systems, Yoram Koren, McGraw Hill Book.

**Course outcomes:**

At the end of the course, the student will be able to:

CO1	Demonstrate basics of industrial automation
CO2	Demonstrate use of automated controls using pneumatic and hydraulic systems
CO3	Identify various types of automation
CO4	Explain the concept of CNC machines and controls
CO5	Prepare CNC part programming for various jobs





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**DIPLOMA IN PRODUCTION ENGINEERING (P05)**  
**SEMESTER V**

COURSE TITLE	:	POWER PLANT ENGINEERING
PAPER CODE	:	7416
SUBJECT CODE	:	511
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objectives:**

- To understand the present scenario of power in India.
- To recognize various load terminologies used in power plants.
- To understand hydro working principles
- To understand working of Diesel, Gas and Nuclear power plants.
- To understand the issues and safety precautions in power plants.

**Course Content:**

**UNIT-I: Introduction to Power plant:** Introduction to power plant; Indian Energy scenario in India; Location of power plant; Choice of Power plant; Classification of power plants.

**Unit-II: Economics of power plant:** Terminology used in power plant: Peak load, Base load, Load factor, Load curve; Various factor affecting the operation of power plant; Methods of meeting the fluctuating load in power plant; Load sharing- cost of power-tariff methods; Performance and operating characteristics of power plant.

**Unit-III: Hydro power plant:** Introduction to Hydro electric power plant; Rainfall, Runoff and its measurement, Hydrograph, flow duration curve; Selection of sites for hydro electric power plant; General layout of Hydro electric power plant and its working; Classification of the Plant-Run off river plant, storage river plant, pumped storage plant; Advantages and disadvantages of hydro electric power plant.

**Unit-IV: Diesel and Gas turbine plant:** The layout of diesel power plant; Components and the working of diesel power plant; Advantages and disadvantages of diesel power plant; Gas turbine power Plant-Schematic diagram, components and its working; Combined cycle power generation- Combined gas and steam turbine power plant operation (only flow diagram).

**Nuclear power plant:** Introduction; Nuclear Power-Radio activity-Radioactive charge-types of reactions; Working of a nuclear power plant; Thermal fission Reactors- PWR, BWR and gas cooled reactors; Advantages and Disadvantages of Nuclear power plant.

**Unit-V: Environmental impact of Power plant:** Social and Economical issues of power plant; Green house effect; Acid precipitation-Acid rain, Acid snow, Dry deposition, Acid fog; Air, water, Thermal pollution from power plants; Radiations from nuclear power plant effluents.

**Power plant safety:** Plant safety concept; Safety policy to be observed in power plants; Safety practices to be observed in boiler operation; Safety in oil handling system; Safety in Chemical handling system; Statutory provision related to boiler operation.

**Reference Books:**

1. Power plant Engineering-P.K. Nag 4<sup>th</sup> edition, Tata McGraw Hill Education, 2014.
2. Power plant Engineering – Frederick T. Morse, Litton Educational Publishing Inc. 1953.
3. A Course in Power Plant Engineering – Subhash C. Arora, S. Domakundwar, Dhanpat Rai, 1984.
4. Power Plant Engineering – P.C. Sharma, S.K.Kataria & sons, 2009.
5. Power System Engineering – R.K. Rajput, Firewell Media,2006.

**Course outcomes**

At the end of the course, the student will be able to:

CO1	Familiarised with the present and future power scenario of India.
CO2	Enlist various load terminologies in power plants
CO3	Working and classifications in hydro power plant
CO4	Working principles of Diesel, Gas and Nuclear power plants.
CO5	Understand the issues and necessity of safety concepts of power plants.

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**DIPLOMA IN PRODUCTION ENGINEERING (P05)**  
**SEMESTER V**

COURSE TITLE	:	FARM EQUIPMENT AND FARM MACHINERY
PAPER CODE	:	7417
SUBJECT CODE	:	512
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Objectives:**

- To find and characterize the machinery based on crop production.
- To find the field efficiency and capacities to calculate the economics of machinery.
- To find the machines usages for different tillage, and its power requirement calculations.
- To understand sowing, planting & transplanting equipment based on crop.
- To understand machinery materials and heat effects for different farm machinery equipment.

**Course Content:**

**UNIT-I:** Introduction to farm mechanization. Classification of farm machines. Unit operations in crop production. Identification and selection of machines for various operations on the farm. Hitching systems and controls of farm machinery.

**Unit-II:** Calculation of field capacities and field efficiency. Calculations for economics of machinery usage, comparison of ownership with hiring of machines. Introduction to seed-bed preparation and its classification. Familiarization with land reclamation and earth moving equipment

**Unit-III:** Introduction to machines used for primary tillage, secondary tillage, rotary tillage, deep tillage and minimum tillage. Measurement of draft of tillage tools and calculations for power requirement for the tillage machines. Introduction to tillage machines like mould-board plough, disc plough, chisel plough, sub-soiler, harrows, puddler, cultivators, identification of major functional components. Attachments with tillage machinery

**Unit-IV:** Introduction to sowing, planting & transplanting equipment. Introduction to seed drills, no-till drills, and strip-till drills. Introduction to planters, bed planters and other planting equipment like sugarcane, potato. Study of types of furrow openers and metering systems in drills and planters. Calibration of seed-drills/ planters. Adjustments during operation.

**Unit-V:** Introduction to materials used in construction of farm machines. Heat treatment processes and their requirement in farm machines. Properties of materials used for critical and functional components of agricultural machines. Introduction to steels and alloys for agricultural application. Identification of heat treatment processes specially for the agricultural machinery components.

**Reference Books:**

1. Principles of Farm Machinery - R.A. Kepner, Roy Bainer, and E. L. Berger
2. Farm Machinery and Equipment - H. P. Smith
3. Farm Machinery and equipment - C. P. Nakra
4. Engineering principles of Agril. Machines - Dr. Ajit K. Srivastav, Caroll E. Goering and Roger P. Rohrbach.
5. Farm Machinery – an Approach - S. C Jain & Grace Phillips
6. Agril. Engineering through worked out examples - Dr. R. Lal and Dr. A.C. Dutta
7. Farm Power and Machinery Engineering - Dr.R. Suresh and Sanjay Kumar

**Course Outcomes:**

At the end of the course, the student will be able to:

C01	Classify the Farm Machineries, equipment and materials
C02	Describe the objectives of Farm mechanization.
C03	Explain selection of the machineries
C04	Discuss the forces acting on tillage tools and hitching systems
C05	Understand the calibration, constructional features and working of various farm equipment.





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**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	ADVANCED MANUFACTURING PROCESSES
PAPER CODE	:	7548
SUBJECT CODE	:	521
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Learning Objectives:**

- To learn about various unconventional machining processes, the various process parameters and their influence on performance and their applications.

**Course Content:**

**UNIT-I: Introduction:** Unconventional machining Process – Need – classification – Brief overview.

**UNIT II: Mechanical Energy Based Processes:** Abrasive Jet Machining, Water Jet Machining, Abrasive Water Jet Machining, Ultrasonic Machining.(AJM, WJM, AWJM and USM). Working Principles – equipment used – Process parameters – MRR- Applications.

**UNIT III: Electrical Energy Based Processes:** Electric Discharge Machining (EDM)- working Principle – equipments – Process Parameters – Surface Finish and MRR- electrode / Tool – Power and control Circuits – Tool Wear – Dielectric – Flushing – Wire cut EDM – Applications.

**UNIT IV: Chemical and Electro-Chemical Energy Based Processes:** Chemical machining and Electro-Chemical machining (CHM and ECM)-Etchants – Maskant techniques of applying maskants - Process Parameters – Surface finish and MRR-Applications . Principles of ECM equipments-Surface Roughness and MRR Electrical circuit-Process Parameters ECG and ECH – Applications.

**UNIT V: Thermal Energy Based Processes:** Laser Beam machining and drilling (LBM), plasma Arc machining (PAM) and Electron Beam Machining (EBM). Principles – Equipment –Types - Beam control techniques – Applications. Introduction to manufacturing; Fundamental properties of materials including metals, polymers, ceramics and composites.

**Reference Books:**

1. Vijay.K. Jain “Advanced Machining Processes” Allied Publishers Pvt. Ltd., New Delhi, 2007
2. Pandey P.C. and Shan H.S. “Modern Machining Processes” Tata McGraw-Hill, New Delhi, 2007.
3. Benedict. G.F. “Non-Traditional Manufacturing Processes”, Marcel Dekker Inc., New York, 1987.
4. Mc Geough, “Advanced Methods of Machining”, Chapman and Hall, London, 1998.
5. Paul De Garmo, J.T.Black, and Ronald.A.Kohser, “Material and Processes in Manufacturing” Prentice Hall of India Pvt. Ltd., 8thEdition, New Delhi , 2001

**Course outcomes:**

At the end of the course, the student will be able to:

C01	Understand various classifications of manufacturing processes
C02	Understand working principles of mechanical energy based processes
C03	Understand working principles of electrical energy based processes
C04	Understand working principles of chemical and electro-chemical energy based processes
C05	Understand working principles of thermal energy based processes

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**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	OPERATIONS RESEARCH
PAPER CODE	:	7549
SUBJECT CODE	:	522
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Learning Objectives:**

- To provide a broad and in depth knowledge of a range of operation research models and techniques, which can be applied to a variety of industrial applications.

**Course Content:**

**UNIT-I:** Development, Definition, Characteristics and phase of Scientific Method, Types of models; General methods for solving operations research models.

**UNIT-II:** Allocation: Introduction to linear programming formulation, graphical solution, Simplex Method, artificial variable technique, Duality principle. Sensitivity analysis.

**UNIT-III:** Transportation Problem Formulation optimal solution. Unbalanced transportation problems, Degeneracy. Assignment problem, Formulation optimal solution.

**UNIT-IV:** Sequencing: Introduction, Terminology, notations and assumptions, problems with n-jobs and two machines, optimal sequence algorithm, problems with n-jobs and three machines.

**UNIT-V:** Theory of games: introduction, Two-person zero-sum games, The Maximum –Minimax principle, Games without saddle points – Mixed Strategies, 2 x n and m x 2 Games – Graphical solutions, Dominance property, Use of L.P. to games.

**Reference Books:**

1. Operations Research: an introduction, Hamdy A. Taha, Pearson Education.
2. Operations. Research: theory and application, J.K. Sharma, Macmillan Publishers.
3. Introduction to Operations Research: concept and cases, Frederick S. Hillier and Gerald J. Lieberman, Tata McGraw-Hill

**Course outcomes:**

At the end of the course, the student will be able to:

C01	Understand the formulation of Liner Programming
C02	Analyze and Convert the problem into a mathematical model.
C03	Understand and implement the transportation problems at workplace
C04	Understand sequencing to optimize the process time for n- job and m-machine
C05	Identify and select suitable methods for various games and apply the LP

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**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	RENEWABLE ENERGY TECHNOLOGIES
PAPER CODE	:	7601
SUBJECT CODE	:	531
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Learning Objectives:**

- To understand present and future scenario of world energy use.
- To understand fundamentals of solar energy systems.
- To understand basics of wind energy.
  
- To understand bio energy and its usage in different ways.
- To identify different available non-conventional energy sources.

**Course Content:**

**UNIT-I: Introduction:** World Energy Use; Reserves of Energy Resources; Environmental Aspects of Energy Utilisation; Renewable Energy Scenario in India and around the World; Potentials; Achievements / Applications; Economics of renewable energy systems.

**Unit-II: Solar energy:** Solar Radiation; Measurements of Solar Radiation; Flat Plate and Concentrating Collectors; Solar direct Thermal Applications; Solar thermal Power Generation Fundamentals of Solar Photo Voltaic Conversion; Solar Cells; Solar PV Power Generation; Solar PV Applications.

**Unit-III: Wind Energy:** Wind Data and Energy Estimation; Types of Wind Energy Systems; Performance; Site Selection; Details of Wind Turbine Generator; Safety and Environmental Aspects.

**Unit-IV: Bio-Energy:** Biomass direct combustion; Biomass gasifiers; Biogas plants; Digesters; Ethanol production; Bio diesel; Cogeneration; Biomass Applications.

**Unit-V: Other Renewable Energy Sources:** Tidal energy; Wave Energy; Open and Closed OTEC Cycles; Small Hydro-Geothermal Energy; Hydrogen and Storage; Fuel Cell Systems; Hybrid Systems.

**Reference Books:**

1. O.P. Gupta, Energy Technology, Khanna Publishing House, Delhi (ed. 2018)
2. Renewable Energy Sources, Twidell, J.W. & Weir, A., EFN Spon Ltd., UK, 2006.
3. Solar Energy, Sukhatme. S.P., Tata McGraw Hill Publishing Company Ltd., New Delhi, 1997.
4. Renewable Energy, Power for a Sustainable Future, Godfrey Boyle, Oxford University Press, U.K., 1996.
5. Fundamental of Renewable Energy Sources, GN Tiwari and MK Ghoshal, Narosa, New Delhi, 2007.
6. Renewable Energy and Environment-A Policy Analysis for India, NH Ravindranath, UK Rao, B Natarajan, P Monga, Tata McGraw Hill.
7. Energy and The Environment, RA Ristinen and J J Kraushaar, Second Edition, John Willey & Sons, New York, 2006.
8. Renewable Energy Resources, JW Twidell and AD Weir, ELBS, 2006.

**Course outcomes:**

At the end of the course, the student will be able to:

CO1	Understand present and future energy scenario of the world.
CO2	Understand various methods of solar energy harvesting.
CO3	Identify various wind energy systems.
CO4	Evaluate appropriate methods for Bio energy generations from various Bio wastes.
CO5	Identify suitable energy sources for a location.





**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	INTERNET OF THINGS
PAPER CODE	:	7602
SUBJECT CODE	:	532
TREORY CREDITS	:	03
PRACTICAL CREDITS	:	00

**Course Content:**

**Unit I** - Introduction to Internet of Things

- Define the term “Internet of Things”
- State the technological trends which have led to IoT.
- Describe the impact of IoT on society.

**Unit II** - Design consideration of IoT

- Enumerate and describe the components of an embedded system.
- Describe the interactions of embedded systems with the physical world.
- Name the core hardware components most commonly used in IoT devices.

**Unit III** Interfacing by IoT devices

- Describe the interaction between software and hardware in an IoT device.
- Explain the use of networking and basic networking hardware.
- Describe the structure of the Internet.

**SUGGESTED LEARNING RESOURCES:**

S. No.	Title of Book	Author	Publication
1	Internet of Things	Raj Kamal	McGraw Hill Education; First edition (10 March 2017) ISBN 978-9352605224
2	internet of Things: A Hands-On Approach	Arsheep Bahge and Vijay Madiseti	Orient Blackswan Private Limited - New Delhi; First edition (2015) ISBN : 978-8173719547

**SUGGESTED SOFTWARE/LEARNING WEBSITES:**

1. <https://www.raspberrypi.org/blog/getting-started-with-iot/>
2. <https://www.arduino.cc/en/IoT/HomePage>
3. <https://www.microchip.com/design-centers/internet-of-things>
4. <https://learn.adafruit.com/category/internet-of-things-iot>
5. <http://esp32.net/>

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**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
 DIPLOMA IN PRODUCTION ENGINEERING (P05)

*SEMESTER V*

COURSE TITLE	:	CAD/CAM LAB
PAPER CODE	:	--
SUBJECT CODE	:	--
TREORY CREDITS	:	00
PRACTICAL CREDITS	:	01

**Course Objectives:**

- To understand the fundamentals and use CAD.
- To conceptualize drafting and modeling in CAD.
- To interpret the various features in the menu of solid modeling package.
- To synthesize various parts or components in an assembly.
- To prepare CNC programmes for various jobs.

**Course Content:**

S.No.	Topics for practice
PART-A	<p><b>Introduction:</b> Part modelling; Datum Plane; constraint; sketch; dimensioning; extrude; revolve; sweep; blend; protrusion; extrusion; rib; shell; hole; round; chamfer; copy; mirror; assembly; align; orient.</p>
	<p>Exercises: 3D Drawings of            1). Geneva Wheel; 2). Bearing Block; 3). Bushed bearing; 4). Gib and Cotter joint; 5). Screw Jack; 6). Connecting Rod:            Note: Print the orthographic view and sectional view from the above assembled 3D drawing.</p>
PART-B	<p><b>CNC Programming and Machining:</b>            Introduction; 1). Study of CNC lathe, milling; 2). Study of international standard codes: G-Codes and M-Codes; 3). Format – Dimensioning methods;            4). Program writing – Turning simulator – Milling simulator, IS practice – commands menus; 5). Editing the program in the CNC machines; 6). Execute the program in the CNC machines;            Exercises:            Note: Print the Program from the Simulation Software and make the Component in the CNC Machine.</p>
	<p><b>CNC Turning Machine:</b> (Material: Aluminium/Acrylic/Plastic rod)            1. Using Linear and Circular interpolation - Create a part program and produce component in the Machine.            2. Using Stock removal cycle – Create a part program for multiple turning operations and produce component in the Machine.            3. Using canned cycle - Create a part program for thread cutting, grooving and produce component in the Machine.</p>

**CNC Milling Machine** (Material: Aluminium/ Acrylic/ Plastic)

1. Using Linear interpolation and Circular interpolation – Create a part program for grooving and produce component in the Machine.
2. Using canned cycle - Create a part program for drilling, tapping, counter sinking and produce component in the Machine.
3. Using subprogram - Create a part program for mirroring and produce component in the Machine.

**Reference Books:**

1. Machine Drawing – P.S. Gill S. K. Kataria & Sons, Delhi., 17th Revised edition, 2001
2. Mechanical Draughtsmanship - G.L. Tamta Dhanpat Rai & Sons, Delhi, 1992
3. Inside AutoCAD – D. Raker and H. Rice, BPB Publications, New Delhi, 1985
4. CAD/CAM/CIM – P. Radhakrishnan, S. Subramanian & V. Raju, New Age International Pvt. Ltd., New Delhi, 3rd Edition,
5. Engineering AutoCAD, A.P. Gautam & Pradeep Jain, Khanna Book Publishing Co., Delhi

**Course outcomes:**

At the end of the course, the student will be able to:

C01	Explain the 3D commands and features of a CAD software
C02	Create 3D solid model and find the mass properties of simples solids
C03	Demonstrate the working of CNC turning and milling machine
C04	Develop the part program using simulation software for Lathe and Milling
C05	Assess the part program, edit and execute in CNC turning and machining centre





**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	SUMMER INTERNSHIP - II
PAPER CODE	:	--
SUBJECT CODE	:	--
TREORY CREDITS	:	00
PRACTICAL CREDITS	:	03

**SUMMER INTERNSHIP - II**

4-6 weeks summer internship after IV<sup>th</sup> Semester.

It should be undertaken in an Industry only.

Evaluation is based on work done, quality of report, performance in viva-voce, presentation etc.

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**DIPLOMA WING**  
**RAJIV GANDHI PROUDYOGIKI VISHWAVIDYALAYA, BHOPAL**  
**DIPLOMA IN PRODUCTION ENGINEERING (P05)**

*SEMESTER V*

COURSE TITLE	:	MAJOR PROJECT
PAPER CODE	:	--
SUBJECT CODE	:	--
TREORY CREDITS	:	00
PRACTICAL CREDITS	:	00 ( ONE CREDIT WILL BE CARRIED FORWARD TO THE VI SEM. MAJOR PROJECT EVALUATION)

**MAJOR PROJECT**

It should be based on real/live problems of the Industry/Govt./NGO/MSME/Rural Sector or an innovative idea having the potential of a Startup.

Evaluation is based on work done, quality of report, performance in viva-voce, presentation etc.

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